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LETTER TO THE EDITOR

Gauge transformation and bi-Hamiltonian structure of a finite-dimensional integrable system reduced from a soliton equation

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Abstract. We present a method for using a gauge transformation to construct a bi-Hamiltonian structure of a finite-dimensional integrable Hamiltonian system reduced from a soliton equation. This is used to construct the bi-Hamiltonian structure for two systems which are related to the second-order polynomial spectral problem and its modified spectral problem, respectively.

Some finite-dimensional integrable Hamiltonian systems have been shown to possess bi-Hamiltonian structures (see, for example, [1-4]). One common way of constructing a bi-Hamiltonian structure is to use the map between two integrable Hamiltonian systems.

In a number of recent papers [5-8], we developed a straightforward way to obtain a hierarchy of finite-dimensional integrable Hamiltonian systems from a hierarchy of integrable nonlinear evolution equations. By restricting the phase space to the invariant subspace of the recursion operator, a constraint on potential can be found and the associated Lax pair under this constraint become finite-dimensional integrable and commuting Hamiltonian systems. On the other hand, there exist gauge transformations between some spectral problems. Thus it is natural to look for a method of constructing the bi-Hamiltonian structure for these kinds of finite-dimensional integrable Hamiltonian systems by using the gauge transformation. We illustrate these ideas by constructing a bi-Hamiltonian structure for the finite-dimensional integrable Hamiltonian systems related to the second-order polynomial spectral problem and its modified spectral problem, respectively.

For the second-order polynomial spectral problem

$$\begin{pmatrix} \phi_1 \\ \phi_2 \end{pmatrix}_x = \begin{pmatrix} 0 & 1 \\ \lambda^m - \sum_{i=0}^{m-1} \lambda^i u_i & 0 \end{pmatrix} \begin{pmatrix} \phi_1 \\ \phi_2 \end{pmatrix} \tag{1}$$

the associated evolution equations given in [9] can be rewritten as [8]

$$u_{i,n} = DL^n u \tag{2}$$

where $D = \partial/\partial x$, $DD^{-1} = D^{-1}D = 1$, $u = (u_0, \dots, u_{m-1})$,

$$L = \begin{pmatrix} 0 & \dots & 0 & J_0 \\ 1 & \dots & 0 & J_1 \\ \dots & \dots & \dots & \dots \\ 0 & \dots & 1 & J_{m-1} \end{pmatrix}$$

$$J_0 = \frac{1}{4}D^2 + u_0 - \frac{1}{2}D^{-1}u_{0x} \quad J_i = u_i - \frac{1}{2}D^{-1}u_{ix} \quad i = 1, \dots, m-1.$$

For distinct λ_j , we now consider the following system

$$\begin{aligned} \phi_{1jx} &= \phi_{2j} \\ \phi_{2jx} &= \left(\lambda_j^m - \sum_{i=0}^{m-1} \lambda_j^i u_i \right) \phi_{1j} \quad j = 1, \dots, N. \end{aligned} \tag{3}$$

By restricting u to the invariant subspace of the recursion operator L , a constraint on u is found as follows in [8]

$$u_0 = \langle \Phi_1, \Phi_1 \rangle + C \tag{4a}$$

$$\begin{aligned} u_{m-k} &= \sum_{i=1}^k (-1)^{i-1} \frac{(i+1)}{2^i} \sum_{l_1+\dots+l_i=k-i} \langle \Lambda^{l_1} \Phi_1, \Phi_1 \rangle \dots \langle \Lambda^{l_i} \Phi_1, \Phi_1 \rangle \\ k &= 1, \dots, m-1 \end{aligned} \tag{4b}$$

where C is a constant; hereafter $l_1 \geq 0, \dots, l_i \geq 0$, $\Phi_1 = (\phi_{11}, \dots, \phi_{1N})^T$, $\Phi_2 = (\phi_{21}, \dots, \phi_{2N})^T$, $\Lambda = \text{diag}(\lambda_1, \dots, \lambda_N)$, $\langle \cdot, \cdot \rangle$ is the inner product in \mathbf{R}^N . Under this constraint on u , (3) becomes a finite-dimensional integrable Hamiltonian system [8]

$$\phi_{1jx} = \frac{\partial H_1}{\partial \phi_{2j}} \quad \phi_{2jx} = -\frac{\partial H_1}{\partial \phi_{1j}} \tag{5a}$$

with

$$H_1 = \frac{1}{2} \langle \Phi_2, \Phi_2 \rangle + \sum_{i=0}^m \left(-\frac{1}{2}\right)^{i+1} \sum_{l_1+\dots+l_{i+1}=m-i} \langle \Lambda^{l_1} \Phi_1, \Phi_1 \rangle \dots \langle \Lambda^{l_{i+1}} \Phi_1, \Phi_1 \rangle + \frac{1}{2} C \langle \Phi_1, \Phi_1 \rangle. \tag{5b}$$

The integrals of the motion in involution for (5a) are given by

$$\begin{aligned} F_k &= \frac{1}{2} \langle \Lambda^{k-1} \Phi_2, \Phi_2 \rangle + \sum_{i=0}^m \left(-\frac{1}{2}\right)^{i+1} \sum_{l_1+\dots+l_{i+1}=m-i} \langle \Lambda^{l_1} \Phi_1, \Phi_1 \rangle \dots \langle \Lambda^{l_i} \Phi_1, \Phi_1 \rangle \\ &\quad \times \langle \Lambda^{l_{i+1}+k-1} \Phi_1, \Phi_1 \rangle + \frac{1}{4} \sum_{j=0}^{k-2} [\langle \Lambda^j \Phi_1, \Phi_1 \rangle \langle \Lambda^{k-2-j} \Phi_2, \Phi_2 \rangle \\ &\quad - \langle \Lambda^j \Phi_1, \Phi_2 \rangle \langle \Lambda^{k-2-j} \Phi_1, \Phi_2 \rangle] + \frac{1}{2} C \langle \Lambda^{k-1} \Phi_1, \Phi_1 \rangle \quad k = 1, 2, \dots \end{aligned} \tag{6}$$

The modified spectral problem for (1) is of the form [9]

$$\begin{pmatrix} \psi_1 \\ \psi_2 \end{pmatrix}_x = \begin{pmatrix} v_0 & \lambda \\ \lambda^{m-1} - \sum_{i=1}^{m-1} \lambda^{i-1} v_i & -v_0 \end{pmatrix} \begin{pmatrix} \psi_1 \\ \psi_2 \end{pmatrix} \tag{7}$$

with $v = (v_0, \dots, v_{m-1})$,

$$u_0 = -v_{0x} - v_0^2 \quad v_i = u_i \quad i = 1, \dots, m-1. \tag{8}$$

From (2) and the Miura transformation (8), it is easy to obtain the evolution equations associated with (7):

$$v_{i_t} = D \tilde{L}^n v \tag{9}$$

with

$$\tilde{L} = \begin{pmatrix} 0 & 0 & \dots & 0 & \tilde{J}_0 \\ -D - 2D^{-1}v_0D & 0 & \dots & 0 & \tilde{J}_1 \\ 0 & 1 & \dots & 0 & \tilde{J}_2 \\ \vdots & \vdots & \dots & \vdots & \vdots \\ 0 & 0 & \dots & 1 & \tilde{J}_{m-1} \end{pmatrix}$$

$$\tilde{J}_0 = -\frac{1}{4}D + \frac{1}{2}v_0 \quad \tilde{J}_i = v_i - \frac{1}{2}D^{-1}v_{ix} \quad i = 1, \dots, m-1.$$

Throughout the letter no boundary condition on u and v is imposed. Firstly we want to reduce an integrable Hamiltonian system from (7) by using the method in [6].

Consider the system

$$\begin{aligned} \psi_{1jx} &= v_0\psi_{1j} + \lambda_j\psi_{2j} \\ \psi_{2jx} &= \lambda_j^{m-1}\psi_{1j} - \sum_{i=1}^{m-1} \lambda_j^{i-1}v_i\psi_{1j} - v_0\psi_{2j} \quad j = 1, \dots, N. \end{aligned} \tag{10}$$

It is easy to verify that if ψ_{1j} and ψ_{2j} satisfy (10), we have

$$\tilde{L}A_j = \lambda_j A_j + \sum_{i=2}^m \beta_i^{(j)} e_i \quad j = 1, \dots, N \tag{11}$$

where $\beta_i^{(j)}$ are integral constants, $e_1 = (1, 0, \dots, 0)^T, \dots, e_m = (0, \dots, 0, 1)^T$,

$$\begin{aligned} A_j &= (A_{j1}, \dots, A_{jm})^T \\ A_{j1} &= -\frac{1}{2}\psi_{1j}\psi_{2j} \\ A_{jk} &= \lambda_j^{m-k}\psi_{1j}^2 - \sum_{i=0}^{m-k-1} \lambda_j^i \tilde{J}_{k+1} \psi_{1j}^2 \quad k = 2, \dots, m-1 \\ A_{jm} &= \psi_{1j}^2. \end{aligned}$$

Notice that

$$\tilde{L} \sum_{i=1}^m \beta_i^{(j)} e_i = \sum_{i=2}^{m-1} \beta_i^{(j)} e_{i+1} + \frac{1}{2}\beta_m^{(j)}. \tag{12}$$

If we take (C_1 is a constant)

$$v = \sum_{j=1}^N A_j + C_1 e_1 \tag{13}$$

we find from (11) and (12) that the linear space spanned by $\{A_1, \dots, A_N, e_1, \dots, e_m\}$ is an invariant subspace of \tilde{L} . This property enables us to obtain the results for system (10) analogous to the theorems in [8]. However, we omit them here.

In a similar manner to [8], (13) leads to the following constraint on v :

$$v_0 = -\frac{1}{2}\langle \Psi_1, \Psi_2 \rangle + C_1 \tag{14a}$$

$$\begin{aligned} v_{m-k} &= \sum_{i=1}^k (-1)^{i-1} \frac{(i+1)}{2^i} \sum_{l_1+\dots+l_i=k-i} \langle \Lambda^{l_1}\Psi_1, \Psi_1 \rangle \dots \langle \Lambda^{l_i}\Psi_1, \Psi_1 \rangle \\ &k = 1, \dots, m-1 \end{aligned} \tag{14b}$$

where $\Psi_1 = (\psi_{11}, \dots, \psi_{1N})^T$, $\Psi_2 = (\psi_{21}, \dots, \psi_{2N})^T$. Under this constraint on v , (10) becomes a Hamiltonian system

$$\psi_{1jx} = \frac{\partial \tilde{H}_1}{\partial \psi_{2j}} \quad \psi_{2jx} = -\frac{\partial \tilde{H}_1}{\partial \psi_{1j}} \quad (15a)$$

with

$$\begin{aligned} \tilde{H}_1 = & -\frac{1}{4} \langle \Psi_1, \Psi_2 \rangle^2 + C_1 \langle \Psi_1, \Psi_2 \rangle + \frac{1}{2} \langle \Lambda \Psi_2, \Psi_2 \rangle \\ & + \sum_{i=1}^m \left(-\frac{1}{2}\right)^i \sum_{l_1 + \dots + l_i = m-i} \langle \Lambda^{l_1} \Psi_1, \Psi_1 \rangle \dots \langle \Lambda^{l_i} \Psi_1, \Psi_1 \rangle. \end{aligned} \quad (15b)$$

We will show later that (15) is an integrable Hamiltonian system.

We find that the gauge transformation

$$\begin{pmatrix} \psi_{1j} \\ \psi_{2j} \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ -\lambda_j^{-1} v_0 & \lambda_j^{-1} \end{pmatrix} \begin{pmatrix} \phi_{1j} \\ \phi_{2j} \end{pmatrix} \quad (16)$$

transforms the modified spectral problem (10) into the spectral problem (3) for fixed j . Under the constraint (14), (16) reads

$$\phi_{1j} = \psi_{1j} \quad (17a)$$

$$\phi_{2j} = \lambda_j \psi_{2j} - \frac{1}{2} \langle \Psi_1, \Psi_2 \rangle \psi_{1j} + C_1 \psi_{1j} \quad (17b)$$

which together with (4a) and (8) leads to

$$C = \tilde{H}_1 - C_1^2. \quad (17c)$$

Since \tilde{H}_1 is constant of motion for (15), (17c) does not contradict the fact that C is a constant. This implies that the transformation $(\Phi_1, \Phi_2, C) = M(\Psi_1, \Psi_2, C_1)$ defined by (17) gives a map between integrable Hamiltonian systems (5) and (15). Following [3, 4], we must extend the phase space to include the constants C and C_1 . Using the notation $\Phi^T = (\Phi_1^T, \Phi_2^T, C)$, $\Psi^T = (\Psi_1^T, \Psi_2^T, C_1)$, the systems (5) and (15) are similarly extended as follows, respectively:

$$\Phi_x = B_1 \frac{\partial H_1}{\partial \Phi} \quad (5a')$$

$$\Psi_x = \tilde{B}_1 \frac{\partial \tilde{H}_1}{\partial \Psi} \quad (15a')$$

where

$$B_1 = \tilde{B}_1 = \begin{pmatrix} 0 & I & 0 \\ -I & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}.$$

Then the Jacobian M' of the map M can be used to construct the second Hamiltonian structure B_2 for the system (5') in the standard way

$$B_2 = M' \tilde{B}_1 M'^T = \begin{pmatrix} 0 & \Lambda - \frac{1}{2} \Phi_1 \otimes \Phi_1 & \Phi_2 \\ -\Lambda + \frac{1}{2} \Phi_1 \otimes \Phi_1 & \frac{1}{2} \Phi_2 \otimes \Phi_1 - \frac{1}{2} \Phi_1 \otimes \Phi_2 & -\partial H_1 / \partial \Phi_1 \\ -\Phi_2^T & (\partial H_1 / \partial \Phi_1)^T & 0 \end{pmatrix}$$

$$H_0 = (\tilde{H}_1 - C_1^2) \circ M^{-1} = C$$

where \otimes denotes tensor product. So the system (5) becomes bi-Hamiltonian:

$$\Phi_x = B_1 \frac{\partial H_1}{\partial \Phi} = B_2 \frac{\partial H_0}{\partial \Phi}. \quad (18)$$

As a special case, when taking $m = 1$ for (1), (18) is just the bi-Hamiltonian structure for the Garnier system given in [4].

The chain equation

$$B_1 \frac{\partial H_{k+1}}{\partial \Phi} = B_2 \frac{\partial H_k}{\partial \Phi} \quad (19)$$

provides an alternative way to generate the integrals of motion for (5). Indeed, starting with $H_0 = C$, we find that H_k generated by (19) are just F_k given by (6). Since C is the Casimir of B_1 , it is easy to show from (19) that F_k are in involution.

Finally we turn to system (15). By substituting (17) into (6), we obtain the integrals of motion for system (15):

$$\begin{aligned} \tilde{F}_{k+1} = & \frac{1}{2} \langle \Lambda^{k+1} \Psi_2, \Psi_2 \rangle - \frac{1}{4} \langle \Psi_2, \Psi_2 \rangle \langle \Lambda^k \Psi_1, \Psi_1 \rangle + C_1 \langle \Lambda^k \Psi_1, \Psi_2 \rangle \\ & \times \frac{1}{4} \sum_{j=0}^k [\langle \Lambda^j \Psi_1, \Psi_1 \rangle \langle \Lambda^{k-j} \Psi_2, \Psi_2 \rangle - \langle \Lambda^j \Psi_1, \Psi_2 \rangle \langle \Lambda^{k-j} \Psi_1, \Psi_2 \rangle] \\ & + \sum_{i=1}^m \left(-\frac{1}{2}\right)^i \sum_{l_1+\dots+l_i=m-i} \langle \Lambda^{l_1} \Psi_1, \Psi_1 \rangle \dots \langle \Lambda^{l_{i-1}} \Psi_1, \Psi_1 \rangle \langle \Lambda^{l_i+k} \Psi_1, \Psi_1 \rangle \\ & k=0, 1, \dots \end{aligned} \quad (20)$$

Since the map (17) is inverse, we can compute a second Hamiltonian structure for system (15). Notice that the Jacobian of an inverse function is just the inverse of the Jacobian of the map; we have

$$\begin{aligned} \tilde{B}_0 = & (M')^{-1} B_1 ((M')^{-1})^T \\ = & \begin{pmatrix} 0 & \Lambda^{-1} - (1/2C_1)\Psi_2 \otimes \Lambda^{-1}\Psi_1 & \partial \tilde{H}_0 / \partial \Psi_2 \\ -\Lambda^{-1} + (1/2C_1)\Lambda^{-1}\Psi_1 \otimes \Psi_2 & E & -\partial \tilde{H}_0 / \partial \Psi_1 \\ -(\partial \tilde{H}_0 / \partial \Psi_2)^T & (\partial \tilde{H}_0 / \partial \Psi_1)^T & 0 \end{pmatrix} \\ \tilde{H}_2 = & H_1 \circ M = \tilde{F}_2 \end{aligned} \quad (21)$$

where

$$\begin{aligned} E = & \frac{1}{C_1} \sum_{i=1}^{m-1} \left(-\frac{1}{2}\right)^i \sum_{l_1+\dots+l_i=m-i-1} \langle \Lambda^{l_1} \Psi_1, \Psi_1 \rangle \dots \langle \Lambda^{l_{i-1}} \Psi_1, \Psi_1 \rangle \\ & \times [(\Lambda^{l_i} \Psi_1) \otimes (\Lambda^{-1} \Psi_1) - (\Lambda^{-1} \Psi_1) \otimes (\Lambda^{l_i} \Psi_1)] \\ \tilde{H}_0 = & \frac{1}{4C_1} \langle \Psi_2, \Psi_2 \rangle - \frac{1}{8C_1} \langle \Psi_2, \Psi_2 \rangle \langle \Lambda^{-1} \Psi_1, \Psi_1 \rangle + \frac{1}{2} \langle \Lambda^{-1} \Psi_1, \Psi_2 \rangle \\ & + \frac{1}{2C_1} \left(1 - \frac{1}{2} \langle \Lambda^{-1} \Psi_1, \Psi_1 \rangle\right) \sum_{i=1}^{m-1} \left(-\frac{1}{2}\right)^i \\ & \times \sum_{l_1+\dots+l_i=m-i-1} \langle \Lambda^{l_1} \Psi_1, \Psi_1 \rangle \dots \langle \Lambda^{l_i} \Psi_1, \Psi_1 \rangle. \end{aligned}$$

Then (15) becomes the bi-Hamiltonian system

$$\Psi_x = \tilde{B}_1 \frac{\partial \tilde{H}_1}{\partial \Psi} = \tilde{B}_0 \frac{\partial \tilde{H}_2}{\partial \Psi}. \quad (22)$$

Using the chain equation

$$\tilde{B}_1 \frac{\partial}{\partial \Psi} \tilde{H}_k = \tilde{B}_0 \frac{\partial}{\partial \Psi} \tilde{H}_{k+1} \quad (23)$$

and starting with $\tilde{H}_1 = \tilde{F}_1$, we find $\tilde{H}_k = \tilde{F}_k$. Since $(\tilde{H}_1 - C_1^2)$ is the Casimir of \tilde{B}_0 , (23) can be used to show that \tilde{F}_k are in involution. Distinct λ_j guarantees that $\tilde{F}_1, \dots, \tilde{F}_N$ are functionally independent. Hence (15) is completely integrable Hamiltonian system in the sense of Liouville.

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